

Connected Automation: Vision, Planning and Initiatives at MDOT

Director Kirk Steudle Michigan Department of Transportation





TOMORROW'S TRANSPORTATION BENEFITS











CONNECTED, AUTOMATED & AUTONOMOUS VEHICLES





Automated

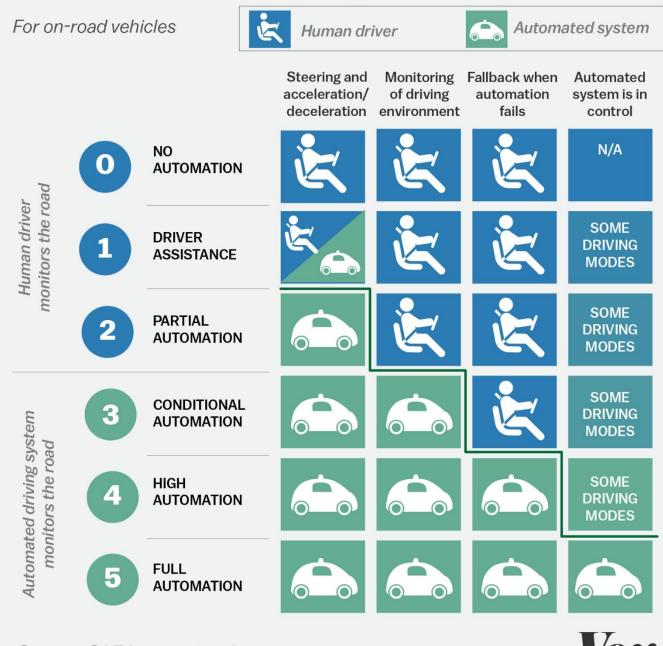




Autonomous

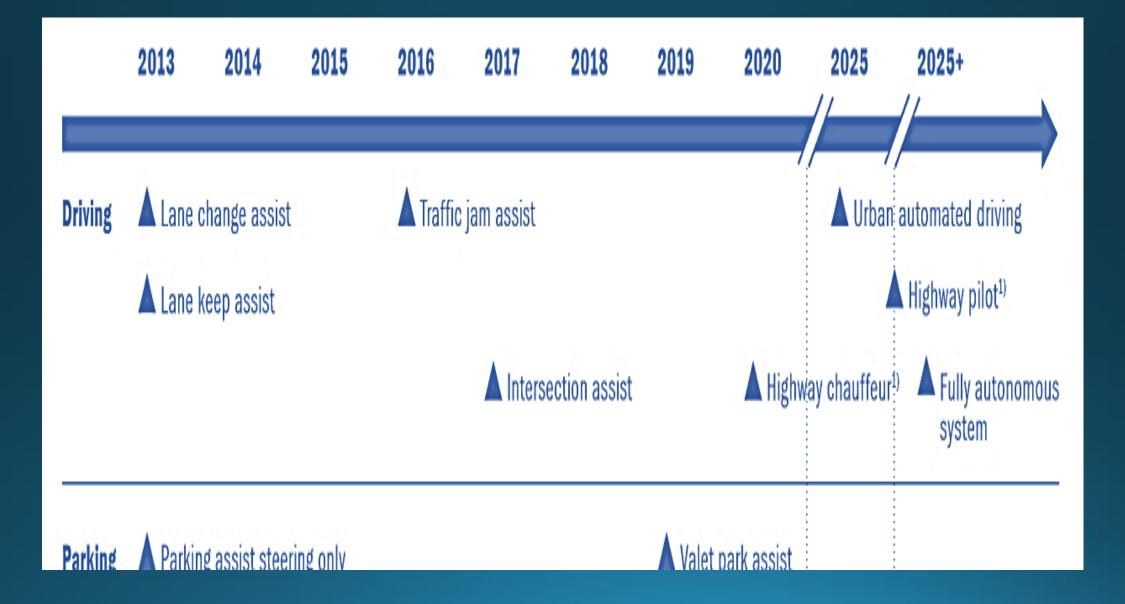
Level 0		Level 1	Level 2	Level 3	Level 4
Driver only		Assisted	Partial	Conditional	Full
e		Active high beam	Traffic jam assist	Collision avoidance	Valet self-parking
Feature		Collision imminent braking	Adaptive cruise & lane keeping	Automated highway	Highway point-to-point
ш́.		Cruise control	Self-parking (with driver)	Automated urban	Urban point-to-point
		Radar	Radar	LIDAR & 360º radar	LIDAR & 360° radar
>		Forward sensors	Forward sensors	High accuracy GPS	High accuracy GPS
olog			Multi-domain controller	Multi-domain controller	Multi-domain controller
Technology			Driver state sensor	Forward, HD & IR cameras	Forward, HD & IR cameras
F			V2X	V2X	V2X
				Internal moment unit	Internal moment unit
		Today		> 2020	> 2025+
					DELPH

The 5 levels of driving automation



Source: SAE International

THE TIMELINE: DRIVERLESS VEHICLE FEATURES





Open Invitation: Michigan's Legislation

996





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BILL No.

SENATE

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KED

SENATE BILL No. 995

May 25, 2016, Introduced by Senators KOWALL, JONES, STAMAS, BRANDENBURG, WARREN, HERTEL, COLBECK, SCHMIDT, MARLEAU, HORN and ANANICH and referred to the Committee on Economic Development and International Introduction

A bill to amend 1949 PA 300, entitled "Michigan vehicle code."

by amending mentions 2D, 602D, 643, 643a, and 665 (MCL 257.2D, 257.602b, 257.643, 257.643a, and 257.665b, sections 2D and 665 as added and section 602b as amended by 2013 PA 201, and by adding sections 40c, 606b, and 665s; and to repeal acts and parts of acts. THE PROPIE OF THE STATE OF MICHIGAN MEMORY.

Sec. 2b. (1) "AUTOMATED DEIVING STSTEM" MEANS HARDWARE AND
SOPTMARE THAT ARE COLLECTIVELY CAPABLE OF PERFORMING ALL ASPECTS OF
SUBMARE THAT ARE COLLECTIVELY CAPABLE ON A PART-THME OR FULL-TIME
BASIS WITHOUT ANT SUPERVISION BY A HYMAN OPERATOR. AS USED IN THIS
SUBMETION, "DYNAMIC DEIVING TANK MEANS ALL OF THE FOLLOWING, BUT
BODES NOT INCLUDE STRATEGIC ASPECTS OF A DRIVING TASK, INCLUDING,

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May 25, 2016, Introduced by Senators KOWALL, JONES, STAMAS, BRANDENBURG, WARREN, HERTEL, COLBECK, SCHMIDT, MARLEAU, HORN and AVANICH and referred to the Committee on Economic Development and International International Investment.

SENATE BILL No. 996



SENATE BILL No. 997

May 25, 2016, Introduced by Senators WARREN, KOWALL, JONES, STAMAS, BRANDENBURG, HERTEL, COLEBCCK, SCHMIDT, MARLEAU, HORN and ANANICH and referred to the Committee on Economic Development and International Investment.

A bill to amend 1949 PA 300, entitled

"Michigan vehicle code," by amending sections Zb and 601a (MCL 257.2b and 257.601a), section 2b as added by 2013 PA 231 and section 601a as amended by 2011 PA

115, and by adding section 665a. THE PEOPLE OF THE STATE OF MICHIGAN ENACT:

L Sec. 2b. (1) "AUTOMATED DRIVING SYSTEM" MEANS HARDWARE AND

2 SOPTWARE THAT ARE COLLECTIVELY CAPABLE OF PERFORMING ALL ASPECTS OF

3 THE DYNAMIC DRIVING TASE FOR A VEHICLE ON A PART-TIME OR FULL-TIME

4 BASIS WITHOUT ANY SUPERVISION BY A HUMAN OPERATOR. AS USED IN THIS 5 SUBSECTION, "DYNAMIC DRIVING TASK" MEANS ALL OF THE FOLLOWING, BUT

6 DOES NOT INCLUDE STRATEGIC ASPECTS OF A DRIVING TASK, INCLUDING,

7 BUT NOT LIMITED TO, DETERMINING DESTINATIONS OF WAYPOINTS:

8 (A) OPERATIONAL ASPECTS, INCLUDING, BUT NOT LIMITED TO.

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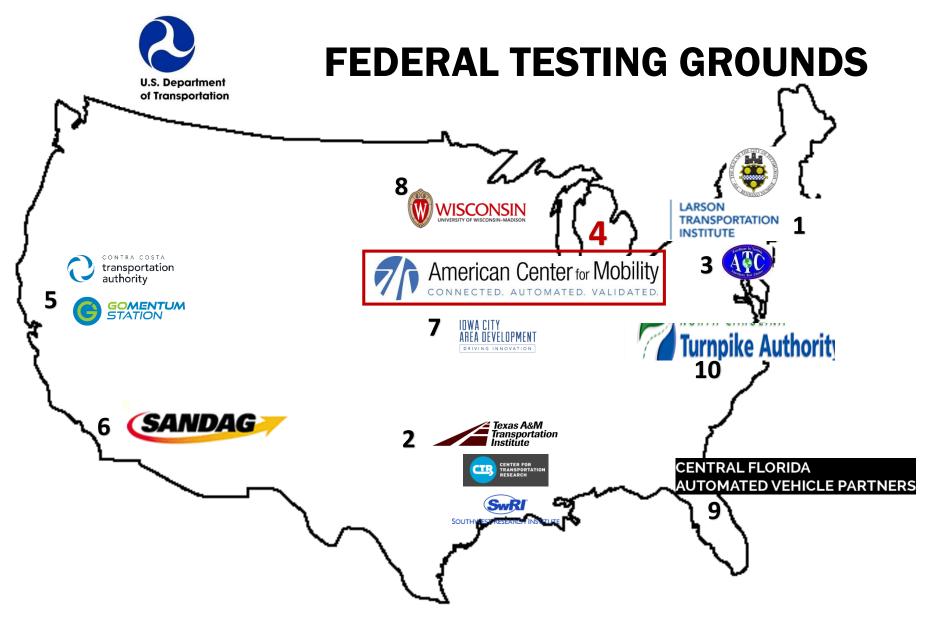
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SENATE BILL No. 998

May 25, 2016, Introduced by Senators HORN, KOWALL, JONES, STAMAS, BRANDENBURG, WARREN, HERTEL, SCHMIDT, MARLEAU and ANANICH and referred to the Committee on Economic Development and International Investment.

A bill to amend 1961 PA 236, entitled
"Revised judicature act of 1961,"
by amending section 2949b (MCL 600.2949b), as added by 2013 PA 251.
THE PROPLE OF THE STATE OF MICHIGAN ENACT:
Sec. 2949b. (1) The manufacturer of a vehicle is not liable
and ehall-MUST be dismissed from any action for alleged damages
resulting from any of the following unless the defect from which
the damages resulted was present in the vehicle when it was
manufactured
(a) The conversion or attempted conversion of the vehicle into
an automated motor vehicle by another person.
(b) The installation of equipment in the vehicle by another

TDR



1. City of Pittsburgh and the Thomas D. Larson Pennsylvania **Transportation Institute** 2. Texas AV Proving Grounds Partnership 3. U.S. Army Aberdeen Test Center 4. American Center for Mobility (ACM) at Willow Run 5. Contra Costa Transportation Authority (CCTA) & GoMentum Station 6. San Diego Association of Governments 7. Iowa City Area Development Group 8. University of Wisconsin-Madison 9. Central Florida Automated Vehicle Partners 10. North Carolina Turnpike Authority

U.S. Army TARDEC















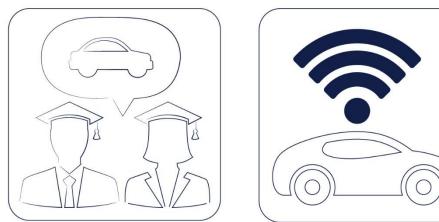
Michigan Council on Future Mobility



https://www.michigan.gov/documents/snyder/MCF_Mobility_report_3_619285_7.pdf

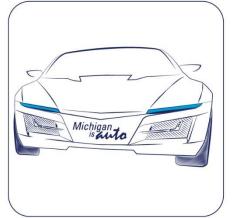


MICHIGAN'S FOCUS



Talent





Industry Awareness



Retention & Attraction



Advocacy



TRANSIT

MDOT values its ability to assist local agency partners in promoting safety and mobility.

SIGNALS

FLEET



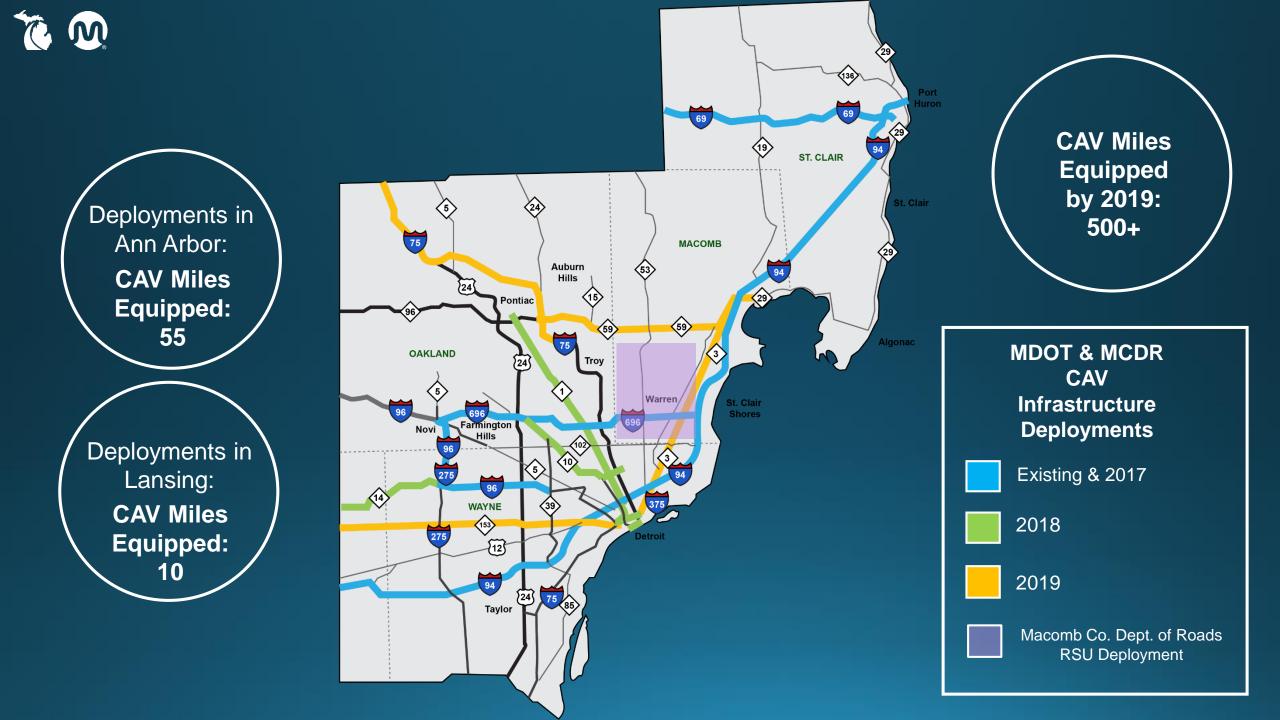
DATA ACCESS



TOGETHER,



This is achieved by sharing best practices and standards developed in the CV and AV environments





MDOT ITS SIGNALS CV INITIATIVE

- CV Enabled Signals Policy
- Signal Controller Spec Update
- All new or upgraded traffic signals on the MDOT system will be CVenabled going forward







YOUR CONNECTED WORK ZONE

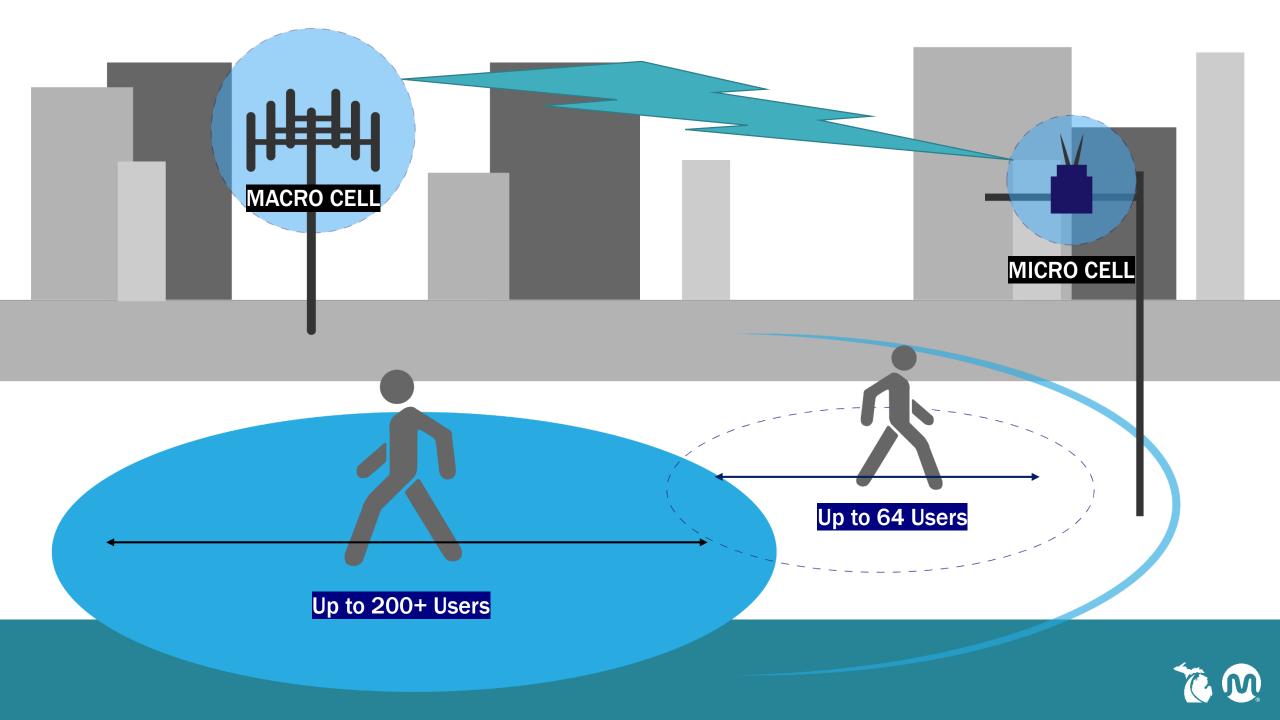




CAV + FIRST RESPONDERS

- Location Information
- Damage/Injury Information
- Signal Priority & Preemption
- Vehicle Detection/Collision Avoidance
- Road Weather Information
- Vehicle Shutdown





Transforming Mobility for the 21st Century

DETROIT $\mathbb{Z}(0)$ **27th Annual Meeting & Expo** ITS America June 4-7 www.itsdetroit2018.org



